Parton Distribution Functions

2024 CTEQ Summer School on QCD and Electroweak Phenomenology

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Summary of Lecture 1

- **4** Parton Distribution functions are a key ingredient of the LHC program
	- \rightarrow PDFs are often the dominant source of uncertainty in theoretical predictions
	- → limiting factor for precision and discovery
- 2 PDFs are related to physical observales via factorisation and evolution
	- \rightarrow qualitative PDF features are driven by this theoretical framework
	- \rightarrow valence peak follows from valence sum rules and kinematic vanishing
	- \rightarrow small-x rise follows from rise of anomalous dimensions
	- \rightarrow correlation of small-x rise and large-x depletion follow from momentum conservation
- ³ PDFs are determined from experimental data by means of parametric regression \rightarrow need to define data, theory, and methodology
- ⁴ Different physical observables constrain different PDF combinations
	- \longrightarrow fixed-target NC DIS: u and d
	- \longrightarrow fixed-target CC DIS: s and \bar{s}
	- \rightarrow HERA NC and CC DIS: u, \bar{u} , d, \bar{d} , g (scaling violations and tagged DIS)
	- \longrightarrow fixed-target DY: u and d at large x
	- \longrightarrow collider DY: u, \bar{u} , d, \bar{d} , s
	- \longrightarrow collider DY+c: s (W) and c (Z)
	- $\longrightarrow Zp_T$, $t\bar{t}$, jets: q

Lecture 2: Theoretical and methodological accuracy in PDF determination

The ingredients of PDF determination

Each of these ingredients is a source of uncertainty in the PDF determination Each of these ingredients require to make choices which lead to different PDF sets

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Overview of current PDF determinations

Parton Distribution Functions Lecture 2: Theoretical and Methodological Accuracy in PDF Determination

Outline

- 2.1 Can we improve the fit quality by improving the theory? heavy quarks and intrinsic charm missing higher order uncertainties electroweak corrections and the photon PDF
- 2.2 Why is the methodology important? parametrisation optimisation uncertainty representation validation of uncertainties PDF benchmarks

I will focus on a limited selection of recent results

I will not talk about some very interesting topics (e.g. a $\mathsf{N}^3\mathsf{LO}$ PDFs, interplay between fitting PDFs and New Physics, non parametric regression models, . . .)

See also lectures by J. Glombitza

2.1 Theory

Can we improve the fit quality by improving the theory?

2.1.1 Heavy Quarks

Heavy Quarks in DIS

Two possible factorisation schemes for DIS structure functions

 $\overline{\text{MS}}$ scheme

Heavy quarks are treated as massless (zero-mass scheme) corrections proportional to $\ln(Q^2/m_h^2)$ are resummed to all orders by <code>DGLAP</code> corrections that are $\mathcal{O}(m_h^2/Q^2)$ are neglected This scheme is appropriate when $Q^2 \gg m_h^2$ Decoupling scheme Heavy quarks are treated as massive (massive scheme) corrections proportional to $\ln(Q^2/m_h^2)$ are treated at fixed order corrections that are $\mathcal{O}(m_h^2/Q^2)$ are included This scheme is appropriate when $Q^2 \sim m_h^2$

The third way: match the two schemes

General-mass variable-flavour number schemes (ACOT, S-ACOT, TR, FONLL, . . .)

use $\overline{\mathrm{MS}}$ for $Q^2 \gg m_h^2$ with full mass dependence retained

keep all flavour sin running DGLAP

subtract double counting terms

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Intrinsic charm in QCD

What is intrinsic charm?

Do not factor charm mass singularities into operator matrix element Choose $n_f = 3$ scheme Charm PDF purely intrinsic, scale-independent Intrinsic charm is charm in the $n_f = 3$ (decoupling) scheme $f_c^{(n_f)} = 0 \rightarrow f_c^{(n_f+1)} \propto \alpha_s \ln \frac{Q^2}{m_c^2} \left(P_{qg} \otimes f_g^{(n_f+1)} \right) + \mathcal{O} \left(\alpha_s^2 \right)$ **NLO** matching **3FNS charm**

How to measure intrinsic charm?

Determine PDFs from data, go to $n_f = 3$ result, look at the result

1) Parametrise PDFs in $n_f = 3$ (3FNS) and match up for fitting

2) Parametrise PDFs in $n_f = 4$ (4FNS) and match down for determining intrinsic charm

Large matching uncertainties [I. Bierenbaum et al.; J. Ablinger et al.]

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Perturbative vs Fitted Charm

Total intrinsic charm

Small but nonzero valence-like intrinsic charm (3FNS)

Stable upon inclusion of MHOUs (estimated as the difference between $NNLO$ and $N³LO$ matching conditions)

Consistence with model predicitons

2.5 σ significance for baseline 3.0 σ with LHCb $Z + c$ and/or EMC F_2^c

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Intrinsic charm-anticharm asymmetry

Small but nonzero charm-anticharm asymmetry (3FNS)

MHOUs estimated as the difference between $NNLO$ and N^3LO matching conditions

1.5 σ significance for baseline 2.5 σ with LHCb $Z + c$ and/or EMC F_2^c

Can be significantly improved at the EIC $\mathcal{A}_{\sigma^{c\bar{c}}}(x,Q^2) \equiv \frac{\sigma_{\rm red}^c(x,Q^2)-\sigma_{\rm red}^{\bar{c}}(x,Q^2)}{\sigma_{\rm red}^{c\bar{c}}(x,Q^2)}$

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2.1.2 Missing Higher Order Uncertainties

Perturbative Accuracy in PDF Determination

NNLO is the precision frontier for PDF determination

N3LO is the precision frontier for partonic cross sections

Mismatch between perturbative order of partonic cross sections and accuracy of PDFs may become a significant source of uncertainty

$$
\hat{\sigma} = \alpha_s^p \hat{\sigma}_0 + \alpha_s^{p+1} \hat{\sigma}_1 + \alpha_s^{p+2} \hat{\sigma}_2 + \mathcal{O}(\alpha_s^{p+3}) \qquad \delta(\text{PDF} - \text{TH}) = \frac{1}{2} \left| \frac{\sigma_{\text{NNLO-PDFs}}^{(2)} - \sigma_{\text{NLO-PDFs}}^{(2)}}{\sigma_{\text{NNLO-PDFs}}^{(2)}} \right|
$$

MHOUs and Scale Variations

As an example, let us consider the NS DIS structure function

$$
F_2^{\text{NS}}(N,Q^2) = xC_{\text{NS}}(N,\alpha_s(Q^2)) \exp\left[\int_{Q_0^2}^{Q^2} \frac{d\lambda^2}{\lambda} \gamma_{\text{NS}}(N,\alpha_s(\mu^2))\right] f_{\text{NS}}(Q_0^2)
$$

Sources of MHOUS

\n
$$
\gamma_{\text{NS}}^{\text{N}^k\text{LO}}(N, \alpha_s) = \alpha_s \gamma_{\text{NS}}^{(0)} + \alpha_s^2 \gamma_{\text{NS}}^{(1)} + \dots \alpha_s^{k+1} \gamma_{\text{NS}}^{(k)}
$$
\n
$$
C_{\text{NS}}^{\text{N}^k\text{LO}}(N, \alpha_s) = 1 + \alpha_s C_{\text{NS}}^{(1)} + \dots \alpha_s^k C_{\text{NS}}^{(k)}
$$

$$
\begin{array}{c} \text{Scale variations}\\ \text{Idea: } \alpha_s(\kappa^2\mu^2)=\alpha_s(\mu^2)[1+\mathcal{O}(\alpha_s)] \end{array}
$$

at N^{k} LO differences due to higher orders are related to the QCD β function up to β_k $\bar{C}_{\rm NS}(\alpha_s(\kappa_r^2\mu^2,\kappa_r^2))=C_{\rm NS}(\alpha_s(\mu^2)) [1+{\cal O}(\alpha_s)]$ fixes $\bar{C}^{(k)}$ in terms of $C^{(k)}$ $\bar{\gamma}_\text{NS}(\alpha_s(\kappa_f^2\mu^2,\kappa_f^2))=\gamma_\text{NS}(\alpha_s(\mu^2)) [1+{\cal O}(\alpha_s)]$ fixes $\bar{\gamma}^{(k)}$ in terms of $\gamma^{(k)}$ $\Delta C_{\rm NS} = \bar{C}_{\rm NS}(\alpha_s(\kappa_r^2\mu^2,\kappa_r^2)) - C_{\rm NS}(\alpha_s(\mu^2))$ renormalisation scale (at which UV divergences are subtracted) $\mu_r = \kappa_r \mu$

$$
\Delta\gamma_{\text{NS}} = \bar{\gamma}_{\text{NS}}(\alpha_s(\kappa_f^2 \mu^2, \kappa_f^2)) - \gamma_{\text{NS}}(\alpha_s(\mu^2))
$$

factorisation scale (at which collinear divergences are factorised) $\mu_f = \kappa_f \mu$

Propagate ΔC and $\Delta \gamma$ into Δf

Scale Variations: Prescriptions

Vary μ_r and μ_f about μ_0

Pick a set of possible variations

3-points: $\mu_r = \mu_f$, $\kappa_{r,f} = 2, 1/2$

7-points: μ_r, μ_f varied independently, $\kappa_{r,f} = 2, 1/2$, remove $\mu_r/\mu_f = 4$

9-points: μ_r, μ_f varied independently, $\kappa_{r,f} = 2, 1/2$

To estimate MHOUs, take the envelope, i.e. the difference between the largest and smallest predictions

A Theory Covariance Matrix

Assuming that theory uncertainties are (a) Gaussian and (b) independent from experimental uncertainties, modify the figure of merit to account for theory errors N_{data} $\chi^2 = \sum^{N_{\rm dat}}$ $\sum_{i,j}^{a_{\text{data}}} (D_i - T_i)(\text{cov}_{\text{exp}} + \text{cov}_{\text{th}})_{ij}^{-1} (D_j - T_j); (\text{cov}_{\text{th}})_{ij} = \frac{1}{N}$ $\frac{1}{N}\sum_{k=1}^{N}$ k $\Delta_i^{(k)} \Delta_j^{(k)}$; $\Delta_i^{(k)} \equiv T_i^{(k)} - T_i$

Problem reduced to estimate the th. cov. matrix, $e.g.$ in terms of nuisance parameters

$$
\Delta_i^{(k)}=T_i(\mu_R,\mu_F)-T_i(\mu_{R,0},\mu_{F,0}); \text{ vary scales in } \tfrac{1}{2}\leq \tfrac{\mu_F}{\mu_{F,0}},\tfrac{\mu_R}{\mu_{R,0}}\leq 2
$$

A Theory Covariance Matrix

Assuming that theory uncertainties are (a) Gaussian and (b) independent from experimental uncertainties, modify the figure of merit to account for theory errors $\chi^2 = \sum^{N_{\rm dat}}$ $\sum_{i,j}^{a_{\text{data}}} (D_i - T_i)(\text{cov}_{\text{exp}} + \text{cov}_{\text{th}})_{ij}^{-1} (D_j - T_j); (\text{cov}_{\text{th}})_{ij} = \frac{1}{N}$ $\frac{1}{N}\sum_{k=1}^{N}$ k $\Delta_i^{(k)} \Delta_j^{(k)}$; $\Delta_i^{(k)} \equiv T_i^{(k)} - T_i$

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Problem reduced to estimate the th. cov. matrix, $e.g.$ in terms of nuisance parameters

Impact on Parton Distributions

Faster perturbative convergence when MHOU are incorporated into PDFs

[EPJ C79 (2019) 838; ibid. 931; EPJ C84 (2024) 517]

Impact on Uncertainties and Fit Quality

Overall (rather small) variation of uncertainties. Tensions relieved: improvement in χ^2 [EPJ C79 (2019) 838; ibid. 931; EPJ C84 (2024) 517]

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What Happens at aN^3LO ?

Fit quality improves with perturbative order

Fit quality almost independent from perturbative order when MHOU are included

Data whose theoretical description is affected by large scale uncertainties are deweighted in favour of more perturbatively stable data

Impact on Inclusive Cross Sections

Effect of using a N^3 LO PDFs instead of NNLO PDFs in N^3 LO predictions is small Good consistency between NNPDF4.0 [EPJ C84 (2024) 659] and MSHT20 [EPJ C83 (2023) 185]

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2.1.3 The photon PDF

Beyond QCD

So far we have considered only the expansion in α_s

But there exist QED and electroweak corrections to partonic cross sections Because $\alpha(M_Z) \sim \alpha_s(M_Z)/10$ we expect NLO EW corrns ~ NNLO QCD corrns

[Slide by courtesy of M. Ubiali]

Let us restrict ourselves to QED corrections

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How should we incorporate QED in our framework?

Define a photon PDF and include it in DGLAP
\n
$$
Q^2 \frac{\partial}{\partial Q^2} g(x, Q^2) = \sum_{q, \bar{q}, g} P_{ga}(x, \alpha_s(Q^2)) \otimes f_a(x, Q^2) + P_{gy}(x, \alpha_s(Q^2)) \otimes \gamma(x, Q^2),
$$
\n
$$
Q^2 \frac{\partial}{\partial Q^2} q(x, Q^2) = \sum_{q, \bar{q}, g} P_{qa}(x, \alpha_s(Q^2)) \otimes f_a(x, Q^2) + P_{q\gamma}(x, \alpha_s(Q^2)) \otimes \gamma(x, Q^2),
$$
\n
$$
Q^2 \frac{\partial}{\partial Q^2} \gamma(x, Q^2) = P_{\gamma\gamma} \otimes \gamma(x, Q^2) + \sum_{q, \bar{q}, g} P_{\gamma a}(x, \alpha_s(Q^2)) \otimes f_a(x, Q^2).
$$

Expand the solution in α_s , α and $\alpha_s \alpha$

$P_{ij} = \sum \left(\frac{\alpha_S}{2\pi}\right)^m \left(\frac{\alpha}{2\pi}\right)^n P_{ij}^{(m,n)}$		
--	--	--

Determine the photon PDF (from data?)

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The LuxQED photon PDF

LUXQED [PRL 117 (2016) 242002]

View the $ep \rightarrow e + X$ process as an electron scattering off the photon field of the proton

Consider a BSM process, e.g. production of a heavy supersymmetric lepton L in ep collision, write the cross section in terms of structure functions and of f_{γ} , and equate the two to obtain f_{γ}

$$
\begin{array}{ll} \sigma = c_0 \sum_a \int_x^1 \frac{dz}{z} \, \hat{\sigma}_a(z,\mu^2) \frac{M^2}{zs} f_{a/p} \left(\frac{M^2}{zs},\mu^2 \right) & x f_{\gamma/p}(x,\mu^2) = \\ \sigma = \frac{c_0}{2\pi} \int_x^{1 - \frac{2\pi m_p}{M}} \frac{dz}{z} \int_{Q_{\min}^2} Q_{\min}^2 \frac{dQ^2}{Q^2} \alpha_{ph}^2(-Q^2) \Biggl[\left(2 - 2z + z^2 \right. & \frac{1}{2\pi \alpha(\mu^2)} \int_x^1 \frac{dz}{z} \left\{ \int_{\frac{u^2}{1 - z}}^{\frac{u^2}{1 - z}} \frac{dQ^2}{Q^2} \alpha^2 (Q^2) \right. \\ \left. + \frac{2x^2 m_p^2}{Q^2} + \frac{z^2 Q^2}{M^2} - \frac{2z Q^2}{M^2} - \frac{2x^2 Q^2 m_p^2}{M^4} \right) F_2(x/z, Q^2) & \left[\left(z p_{\gamma q}(z) + \frac{2x^2 m_p^2}{Q^2} \right) F_2(x/z, Q^2) - z^2 F_L \left(\frac{x}{z}, Q^2 \right) \right. \\ \left. + \left(-z^2 - \frac{z^2 Q^2}{2M^2} + \frac{z^2 Q^4}{2M^4} \right) F_L(x/z, Q^2) \right] & - \alpha^2 (\mu^2) z^2 F_2 \left(\frac{x}{z}, \mu^2 \right) \Biggr\} \end{array}
$$

Iterate a QCD fit including f_{γ} in DGLAP and in the momentum sum rule

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Implications for PDFs and LHC processes

Fit quality unaltered: $\chi^2/N_{\rm dat}=0.17$ Small (0.5%) momentum shift from q to γ Small (1%) suppression of the gluon PDF 1-2% suppression in qgH cross section

 $10²$

Q [GeV]

 $10¹$ Emanuele R. Nocera (UNITO) [Parton Distribution Functions](#page-0-0) 28 August 2024 28/64

48

46

 44 M[g(Q)][%]

42

40 38

36

NNPDF4.00ED NNPDF4.0

 $10³$

2.2 Methodology

Why is the methodology important?

The methodology is crucial if we aim at percent-level accurate PDFs

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What are the ingredients of a fitting methodology?

parametrisation

polynomials/neural network(s) is there a bias due to the parametrisation?

optimisation

(adaptive) gradient descent is the parameter space explored efficiently?

uncertainty representation

Hessian/bootstrap of experimental uncertainties what is the statistical meaning of uncertainties?

validation

closure tests (what happens if I know in advance the underlying law that I am fitting?) are interpolation and extrapolation uncertainties statistically faithful?

benchmark

PDF4LHC working group

are PDFs obtained independently by various groups equivalent?

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2.2.1 Parametrisation

Parametrisation: general features

Problem projected onto the finite-dimensional space of parameters

Choose a parametrisation at an initial scale Q_0^2 for each independent parton i (or a combination of them)

$$
xf_i(z, Q_0^2) = A_i x^{a_i} (1-x)^{b_i} \mathscr{F}_i(x, \{c_{f_i}\})
$$

The problem is reduced to the determination of the finite set of parameters $\{c_{f_i}\}$

The interpolating function $\mathscr{F}_i(x,\{c_{f_i}\})$ should be sufficiently GENERAL (the range of PDF behaviours in the space of functions should not be limited) SMOOTH (PDFs are implicitly assumed ot be smooth functions) FLEXIBLE (it should be able to adapt to a variety of data and processes) to describe the data with minimal bias

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Parametrisation: two alternative choices

1 Polynomial (Bernstein, Chebyschev) parametrisation, e.g.

$$
\mathcal{F}_i = 1 + \sum_{i=1}^n a_i T_i^{\text{Ch}}(y(x)) \qquad y = 1 - 2\sqrt{x}
$$

in terms of a (relatively) small set of parameters $(\mathcal{O}(30)$ per PDF set)

$$
\{{\bf a}\}=\{a_i,b_i,\gamma_i,\delta_i\}
$$

 \Rightarrow smooth behavior (a desirable feature for a PDF)

 \Rightarrow potential source of bias if the parametrisation is too rigid

2 Redundant parametrisation, e.g.

a neural network

in terms of a huge set of parameters $(\mathcal{O}(200)$ per PDF set)

$$
\{{\bf a}\}=\{\omega_{ij}^{(L-1),f_i},\theta_i^{(L),f_i}\}
$$

- ⇒ potentially non-smooth
- \Rightarrow bias due to the parametrisation reduced as much as possible

Parametrisation: what a neural network exactly is?

A convenient functional form providing a flexible parametrization used as a generator of random functions in the PDF space

EXAMPLE: MULTY-LAYER FEED-FORWARD PERCEPTRON

$$
\xi_i^{(l)} = g\left(\sum_j^{n_l-1} \omega_{ij}^{(l-1)} \xi_j^{(l-1)} - \theta_i^{(l)}\right)
$$

$$
g(y) = \frac{1}{1 + e^{-y}}
$$

- made of neurons grouped into layers (define the architecture)
- **•** each neuron receives input from neurons in the preceding layer (feed-forward NN)
- activation $\xi_i^{(l)}$ determined by a set of parameters (weights and thresholds)
- activation determined according to a non-linear function (except the last layer)

Parametrisation: what a neural network exactly is?

EXAMPLE: THE SIMPLEST 1-2-1 MULTI-LAYER FEED-FORWARD PERCEPTRON

$$
f(z) \equiv \xi_1^{(3)} = \left\{1+\exp\left[\theta_1^{(3)}-\frac{\omega_{11}^{(2)}}{1+e^{\theta_1^{(2)}-x\omega_{11}^{(1)}}}-\frac{\omega_{12}^{(2)}}{1+e^{\theta_2^{(2)}-x\omega_{21}^{(1)}}}\right]\right\}^{-1}
$$

Recall:
$$
\xi_i^{(l)} = g\left(\sum_j^{n_l-1} \omega_{ij}^{(l-1)} \xi_j^{(l-1)} - \theta_i^{(l)}\right); \quad g(z) = \frac{1}{1+e^{-z}}
$$

Parametrisation: standard vs redundant

HERA-LHC 2009 PDF benchmark

2.2.2 Optimisation

Fit quality

 $\textbf{\textcolor{black}{\bullet}}$ Define the fit quality (the χ^2 function)

$$
\chi^2 = \sum_{i,j}^{N_{\rm dat}} \left(T_i[\{\mathbf{a}\}] - D_i \right) \left(\operatorname{cov}^{-1} \right)_{ij} \left(T_j[\{\mathbf{a}\}] - D_j \right)
$$

with the experimental covariance matrix

$$
\left(\textrm{cov}\right)_{ij} = \delta_{ij} s_i^2 + \left(\sum_{\alpha}^{N_c} \sigma_{i,\alpha}^{(c)} \sigma_{j,\alpha}^{(c)} + \sum_{\alpha}^{N_{\mathcal{L}}} \sigma_{i,\alpha}^{(\mathcal{L})} \sigma_{j,\alpha}^{(\mathcal{L})} \right) D_i D_j
$$

- s_i are N_{dat} uncorrelated uncertainties (statistic + uncorrealted systematic ucnertainties) $\sigma_{i,\alpha}^{(c)}$ are $N_{\rm dat}\times N_c$ additive correlated uncertainties $\sigma_{i,\alpha}^{(\mathcal{L})}$ are $N_{\text{dat}} \times N_{\mathcal{L}}$ multiplicative uncertainties
- $\textbf{2}$ Find the best-fit configuration of parameters $\{\mathbf{a_0}\}$ which minimise the χ^2
- Treat conveniently
	- \blacktriangleright uncorrelated/correlated uncertainties need not to overestimate uncertainties and to let the χ^2 be faithful
	- \blacktriangleright additive/multiplicative uncertainties need to avoid the D'Agostini bias

Parameter optimisation: general framework

Optimisation usually performed by means of simple gradient descent: compute and minimise the gradient of the fit quality with respect to the fit parameters

$$
\frac{\partial \chi^2}{\partial a_i}, \qquad \text{for } i = 1, \dots, N_{\text{par}}
$$

Optimisation should minimise the noise in the χ^2 driven by noisy experimental data

Additional complications in case of a redundant parametrisation (huge parameter space)

- \bullet need to explore the parameter space as uniformly as possible (in order to avoid stopping the fit in a local minimum)
- ² need for a computationally efficient minimisation (non-trivial relationship between FFs and observables via convolution)
- ³ need to define a criterion for minimisation stopping (avoid learning statistical fluctuations of the data)

Alternative algorithms: genetic algorithms, adaptive algorithms, . . .

$$
\chi^2 = \sum_{i,j}^{N_{\text{dat}}} (T_i[\{\mathbf{a}\}] - D_i) (\text{cov}^{-1})_{ij} (T_j[\{\mathbf{a}\}] - D_j)
$$

$$
(\text{cov})_{ij} = \delta_{ij} s_i^2 + \left(\sum_{\alpha}^{N_c} \sigma_{i,\alpha}^{(c)} \sigma_{j,\alpha}^{(c)} + \sum_{\alpha}^{N_c} \sigma_{i,\alpha}^{(\mathcal{L})} \sigma_{j,\alpha}^{(\mathcal{L})}\right) D_i D_j
$$

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Optimisation: stopping criterion

Divide the data into two subsets (training & validation) Train the NN on the training subset and compute χ^2 for each subset Stop when the training loss reaches the absolute minimum

The best fit does not coincide with the absolute minimum of the χ^2

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Hypertoprimisation: fitting the methodology

Compare to a Test Set (new set of data previously not used at all) Who picks the Test Set? Automatic generalisation based on K foldings Divide the data into n representative sets, fit $n-1$ sets and use the n-th set as test set Hyperoptimise on mean and standard deviation of $\chi^2_{\text{test},i},\, i=1\ldots n$

Hyperoptimisation: K-folding

Compare to a Test Set (new set of data previously not used at all) Who picks the Test Set? Automatic generalisation based on K foldings Divide the data into n representative sets, fit $n-1$ sets and use the n-th set as test set Hyperoptimise on mean and standard deviation of $\chi^2_{\text{test},i},\, i=1\ldots n$

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Hyperparameters

2.2.3 Uncertainty representation

The Hessian method: general strategy

 $\textbf D$ Expand the χ^2 about its global minimum at first (nontrivial) order

$$
\chi^2\{\mathbf{a}\} \approx \chi^2\{\mathbf{a_0}\} + \delta a^i H_{ij}\delta a^j, \qquad H_{ij} = \frac{1}{2} \left. \frac{\partial^2 \chi^2\{\mathbf{a}\}}{\partial a_i \partial a_j} \right|_{\{\mathbf{a}\} = \{\mathbf{a_0}\}}
$$

Assume linear error propagation for any observable $\mathcal O$ depending on $\{a\}$

$$
\langle \mathcal{O}\{\mathbf{a}\}\rangle \approx \mathcal{O}\{\mathbf{a_0}\} + a_i \left. \frac{\partial \mathcal{O}\{\mathbf{a}\}}{\partial a_i}\right|_{\{\mathbf{a}\}=\{\mathbf{a_0}\}} \qquad \sigma_{\mathcal{O}\{\mathbf{a}\}} \approx \sigma_{ij} \frac{\partial \mathcal{O}\{\mathbf{a}\}}{\partial a_i} \left. \frac{\partial \mathcal{O}\{\mathbf{a}\}}{\partial a_j}\right|_{\{\mathbf{a}\}=\{\mathbf{a_0}\}}
$$

3 Determine σ_{ij} from H_{ij} from maximum likelihood (under Gaussian hypothesis)

$$
\sigma_{ij}^{-1} = \left. \frac{\partial^2 \chi^2 \{\mathbf{a}\}}{\partial a_i \partial a_j} \right|_{\{\mathbf{a}\} = \{\mathbf{a_0}\}} = H_{ij}
$$

⁴ A C.L. about the best fit is obtained as the volume (in parameter space) about $\chi^2\{{\bf a_0}\}$ that corresponds to a fixed increase of the $\chi^2;$ for Gaussian uncertainties:

68% C.L.
$$
\Longleftrightarrow \Delta \chi^2 = \chi^2 {\mathbf{a}} - \chi^2 {\mathbf{a}}_0 = 1
$$

The Hessian method: some remarks

4 Compact representation and computation of observables and their uncertainties

 $\langle \mathcal{O}[f(x,Q^2)] \rangle = \mathcal{O}[f_0(x,Q^2)]$

$$
\sigma_{\mathcal{O}}[f(x, Q^2)] = \frac{1}{2} \left[\sum_{i=1}^{N_{\text{par}}} \left(\mathcal{O}[f_i(x, Q^2)] - \mathcal{O}[f_0(x, Q^2)] \right)^2 \right]^{1/2}
$$

2 Parameters can always be adjusted so that all eigenvalues of H_{ij} are equal to one (diagonalise H_{ij} and rescale the eigenvectors by their eigenvalues)

$$
\delta a_i H_{ij} \delta a_j = \sum_{i=1}^{N_{\text{par}}} \left[a_i'(a_i) \right]^2 \Longleftrightarrow \sigma_{\mathcal{O}\{\mathbf{a}'\}} = \left| \nabla' \mathcal{O}\{\mathbf{a}'\} \right|
$$

The total contribution to the uncertainty due to two different sources (possibly correlated) is obtained by simply adding them in quadrature

- ³ Any rotation in the space of parameters preserves the gradient (one can diagonalise a chosen observable without spoiling the result)
- ⁴ Unmanageable Hessian matrix if the numer of parameters is huge

The Hessian method: limitations

Uncertainties obtained with $\Delta\chi^2=1$ might be unrealistically small (inadequacy of the linear approximation)

uncertainties tuned to the distribution of deviations from best-fits for single experiments

for each eigenvector in parameter space

determine the CL for the distribution of best-fits of each experiment

rescale to the $\Delta\chi^2=T$ interval such that correct confidence intervals are reproduced

no statistically rigorous interpretation of T (tolerance)

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The Monte Carlo method: general strategy

4 Generate (art) replicas of (exp) data according to the distribution

$$
\mathcal{O}_i^{(art)(k)} = \mathcal{O}_i^{(exp)} + r_i^{(k)} \sigma_{\mathcal{O}_i}, \qquad i = 1, \dots N_{\text{dat}}, \qquad k = 1, \dots, N_{\text{rep}}
$$

where $r_i^{(k)}$ are (Gaussianly distributed) random numbers for each $k\text{-th}$ replica $(r_i^{(k)}$ can be generated with any distribution, not neccesarily Gaussian)

- **2** Perform a fit for each replica $k = 1, ..., N_{\text{rep}}$
- **3** Compact computation of observables and their uncertainties (PDF replicas are equally probable members of a statistical ensemble)

$$
\langle \mathcal{O}[f(x,Q^2)] \rangle = \frac{1}{N_{\sf rep}} \sum_{k=1}^{N_{\sf rep}} \mathcal{O}[f^{(k)}(x,Q^2)]
$$

$$
\sigma_{\mathcal{O}}[f(x,Q^2)] = \left[\frac{1}{N_{\mathsf{rep}}-1}\sum_{k=1}^{N_{\mathsf{rep}}}\left(\mathcal{O}[f^{(k)}(x,Q^2)]-\langle\mathcal{O}[f(x,Q^2)]\rangle\right)^2\right]^{1/2}
$$

- \Rightarrow no need to rely on linear approximation
- \Rightarrow computational expensive: need to perform N_{rep} fits instead of one

The Monte Carlo method: determining the sample size

Require that the average over the replicas reproduces the central value of the original experimental data to a desired accuracy (the standard deviation reproduces the error and so on)

Accuracy of few % requires ~ 100 replicas

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2.2.4 Validation

Closure tests: general idea [JHEP 1504 (2015) 040]

Validation and optimisation of the fitting strategy with known underlying physical law

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Closure Tests: Levels

interpolation uncertainty fuctional uncertainty data uncertainty

Level 0 Level 1 Level 2

no fluctuations Gaussian fluctuation Monte Carlo replicas

Closure tests at work

1.20

1.15

1.10 1.05 1.00 0.95 0.90 0.85 0.80 $\frac{10^{-5}}{10^{-5}}$

 10^{-4}

 10^{-3}

 10^{-2}

 10^{-1}

Data region: closure tests

Fit PDFs to pseudodata generated assuming a known underlying law

Define bias and variance bias difference of central prediction and truth variance uncertainty of replica predictions

> If PDF uncertainty faithful, then $E[bias] = variance$ 25 fits, 40 replicas each

Pyel₂

 PVA 1 level 0

 $10⁰$

level 2

level 1 level 0

າ່ດ.

Size of uncertainty on g at 1.65 GeV

Future tests

Extrapolation regions: future test

Test PDF uncertainties on data sets not included in a given PDF fit that cover unseen kinematic regions

Only exp. cov. matrix

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Future tests

Extrapolation regions: future test

Test PDF uncertainties on data sets not included in a given PDF fit that cover unseen kinematic regions

Exp+PDF cov. matrix

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2.2.5 Benchmarks

Overview of current PDF determinations

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Making predictions with PDFs

[Acta Phys.Polon.B 53 (2022) 12]

2.3 Summary of Lecture 2

Summary of Lecture 2

1 PDF accuracy can be improved by improving the theory

- → proper treatment of heavy quarks is mandatory to describe DIS data
- \rightarrow evidence for intrinsic charm in the proton
- → MHOUs can be estimated by scale variations
- → inclusion of MHOUs stabilises fit quality
- \rightarrow electroweak corrections modify DGLAP equations
- \rightarrow the photon PDF is determined very precisely
- \rightarrow inclusion of photon PDFs impacts the gluon PDF
- **2** Devising the methodology is essential to minimise bias and variance
	- \rightarrow bias is a measure of accuracy, variance is a measure of precision
	- \rightarrow choices of parametrisation (polynomial vs neural network)
	- \rightarrow choices of uncertainty representation (Hessian vs Monte Carlo)
	- −→ are all sources of bias and variance
	- \rightarrow closure tests are a way to validate PDF uncertainites in the seen region
	- \rightarrow future tests validate the generalisation power in the *unseen* region

Thank you