# Introduction to Monte Carlo generators: Matrix Elements

Rikkert Frederix Lund University





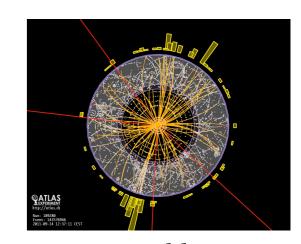
# Bridging the gap

### Theory

Lagrangian
Gauge invariance
QCD
BSM parameters

...





Detector calibration
Pions, Kaons, ...
Reconstruction
B-tagging efficiency

. .

Experiment

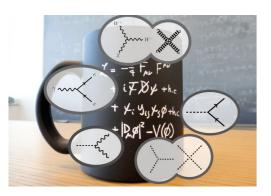


# Bridging the gap

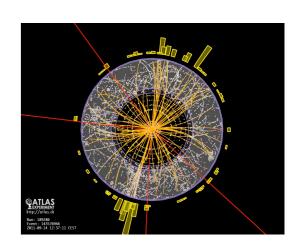
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• • •







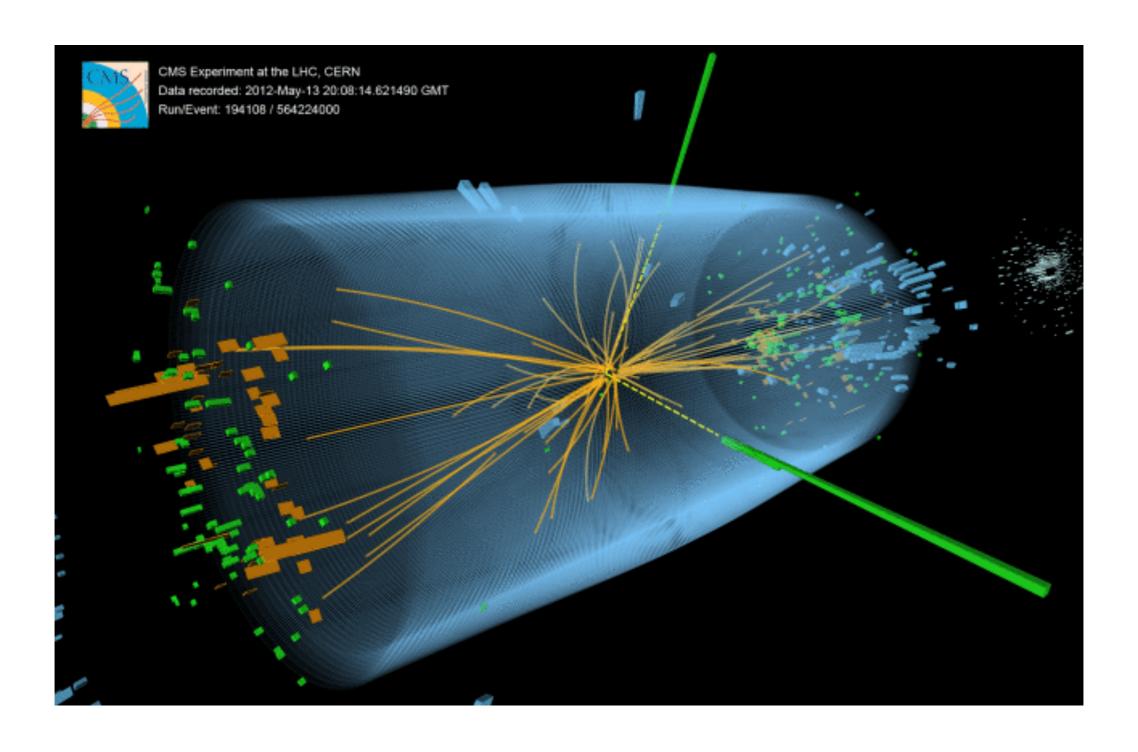
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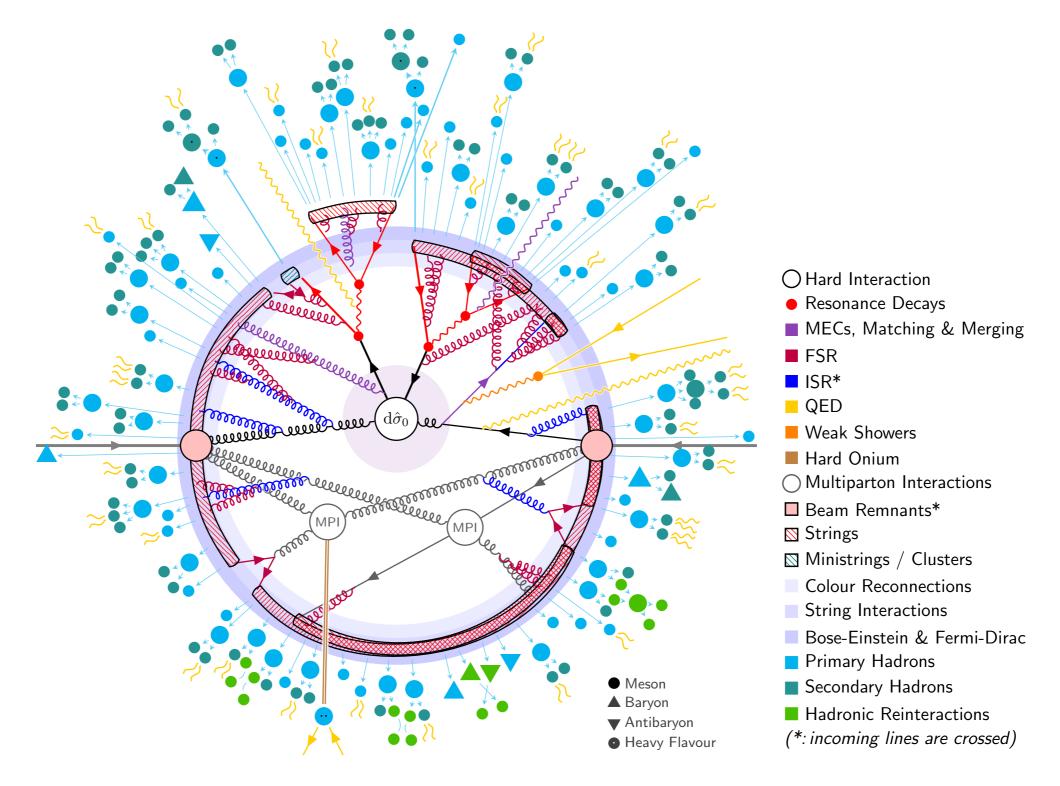


# Event display Experimentalist's point of view



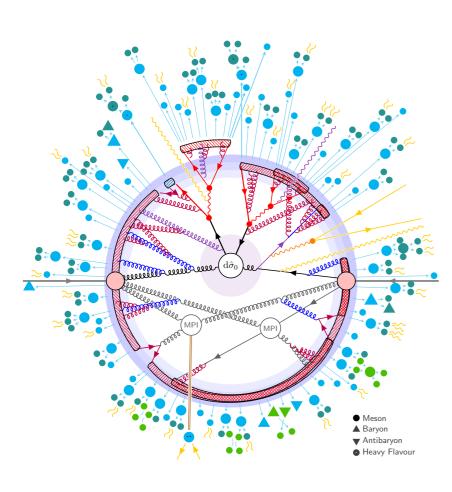






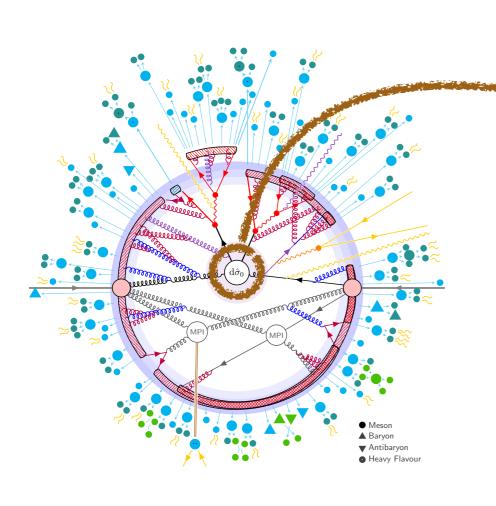


### The hard interaction





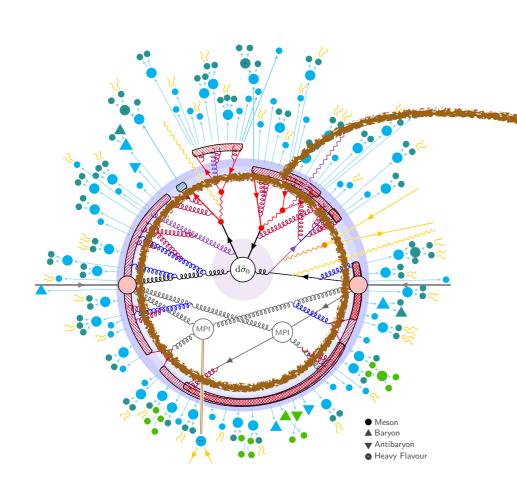
### The hard interaction



- Core of the event
- Process dependent
- First principles description
  - Largest energy transfers
  - New physics most-likely will appear here
  - Can use perturbation theory: LO, NLO, NNLO, etc.



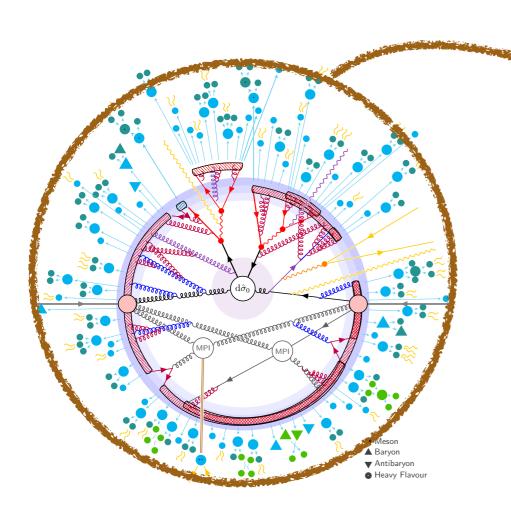
### The Parton Shower



- Known QCD: first principles description
- Universal/process independent
- Can systematically be improved using perturbation theory



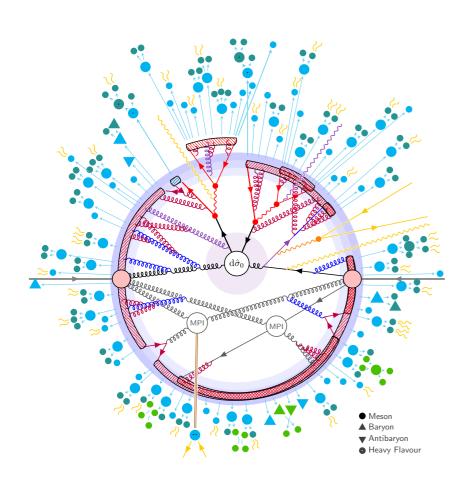
# Hadronisation & Underlying event



- Low Q<sup>2</sup> physics
- Process and energy independent
- Based on models (motivated by physics)



### Lecture 1: the hard interaction

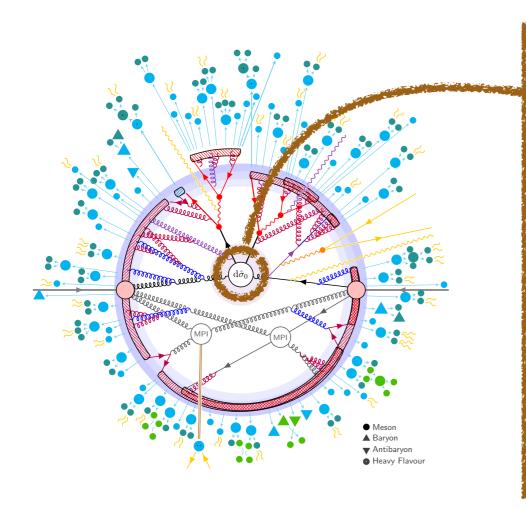


Lecture 2: Parton Showers & Hadronisation

Lecture 3: Matching & Merging



### Lecture 1: the hard interaction



- Core of the event
- Process dependent
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  - Largest energy transfers
  - New physics most-likely will appear here
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Lecture 2: Parton Showers & Hadronisation

Lecture 3: Matching & Merging



# Master equation for the hard interaction

$$\sum_{a,b} \int dx_1 dx_2 d\Phi_{\mathrm{FS}} \, f_a(x_1,\mu_F) f_b(x_2,\mu_F) \, \hat{\sigma}_{ab \to X}(\hat{s},\mu_F,\mu_R)$$
 Phase-space Parton density Parton-level cross integral functions section

#### 1. Parton distribution functions

- Universal/process independent
- Extracted from experiment
- Evolution from theory
  - Can be extract in one process, and applied to others

#### 2. Parton-level cross section

- Short distance coefficients as an expansion in α<sub>S</sub>
- From theory



$$\hat{\sigma}_{ab\to X}(\hat{s},\mu_F,\mu_R)$$
 Parton-level cross section

$$\hat{\sigma} = \sigma^{\text{Born}} \left( 1 + \frac{\alpha_s}{2\pi} \sigma^{(1)} + \left( \frac{\alpha_s}{2\pi} \right)^2 \sigma^{(2)} + \left( \frac{\alpha_s}{2\pi} \right)^3 \sigma^{(3)} + \dots \right)$$



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LO
predictions

NLO
corrections



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# Higher-order computations

• Why?

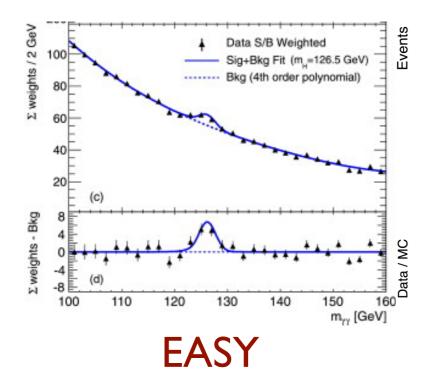
They improve the accuracy of our predictions



### Discoveries at hadron colliders

#### Peak

 $H \rightarrow \gamma \gamma$ 



Background directly measured from data.

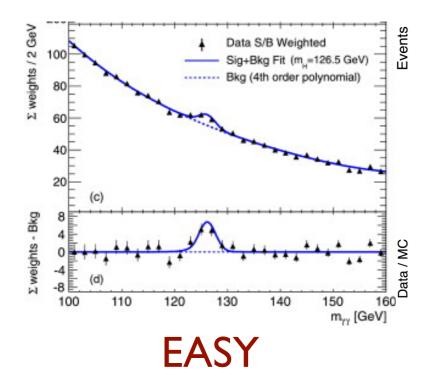
Theory needed only for parameter extraction



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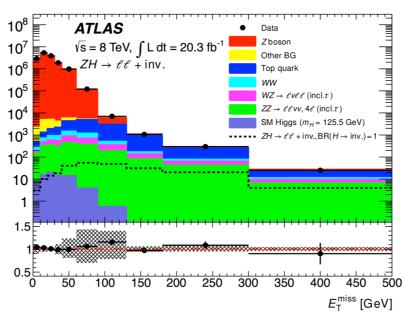


Background directly measured from **data**.

Theory needed only for parameter extraction

#### Shape

 $ZH \rightarrow l^+l^- + inv.$ 



#### **HARD**

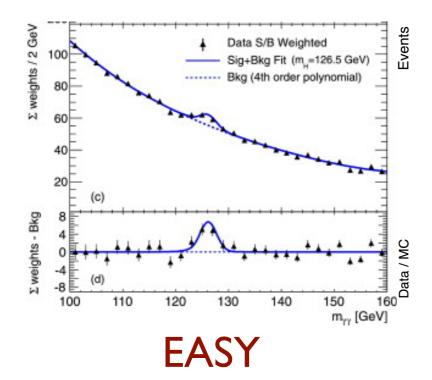
Background **SHAPE** needed. Flexible MC for both signal and background validated and tuned to data



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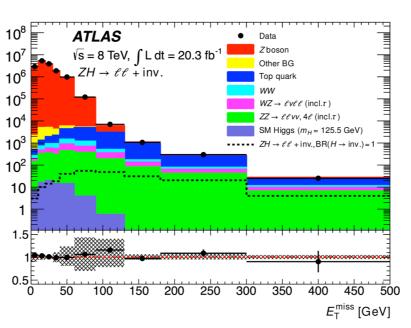


Background directly measured from **data**.

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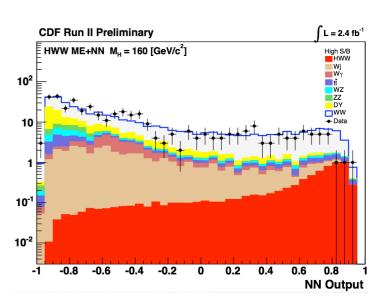


#### **HARD**

Background **SHAPE** needed. Flexible MC for both signal and background validated and tuned to data

#### Rate

 $H \rightarrow W^+ W^-$ 



#### **VERY HARD**

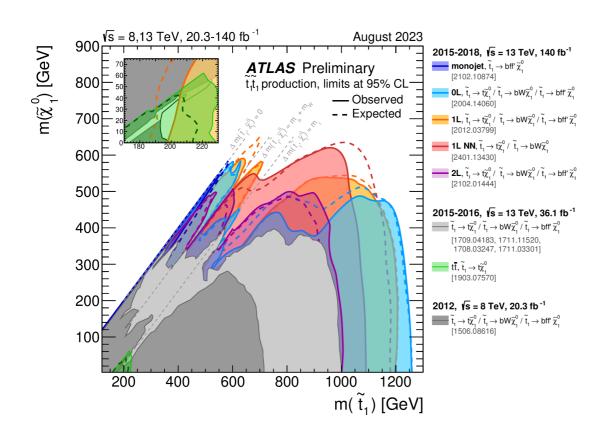
Relies on prediction for both shape and normalization.

Complicated interplay of best simulations and data

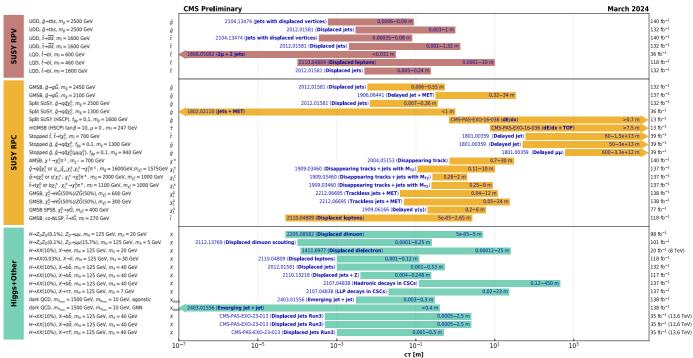


# New Physics?

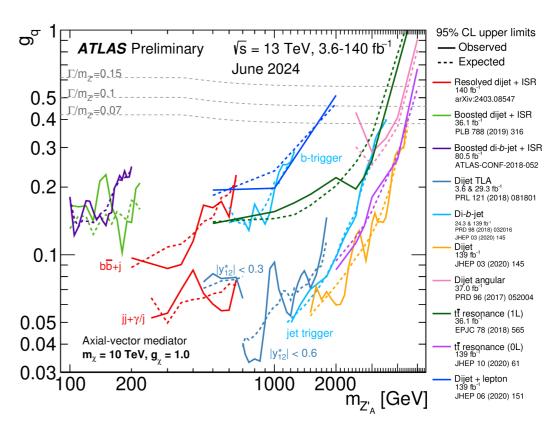
- No NP has been discovered yet
  - Either there is no NP, or it is hiding very well
  - If it is there, it will be a 'Hard' or 'very Hard' discovery
  - Need for accurate predictions for signal and background



#### **Overview of CMS long-lived particle searches**



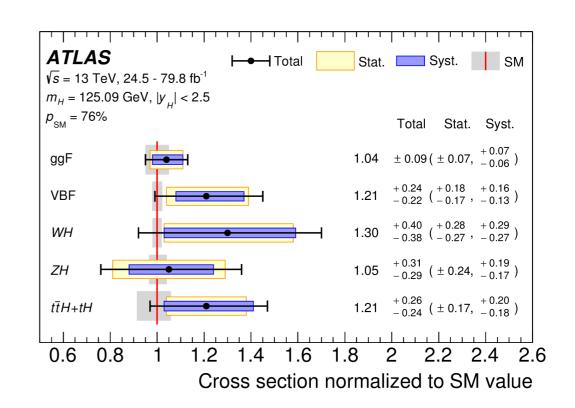
election of observed exclusion limits at 95% C.L. (theory uncertainties are not included). The y-axis tick labels indicate the studied long-lived particle.

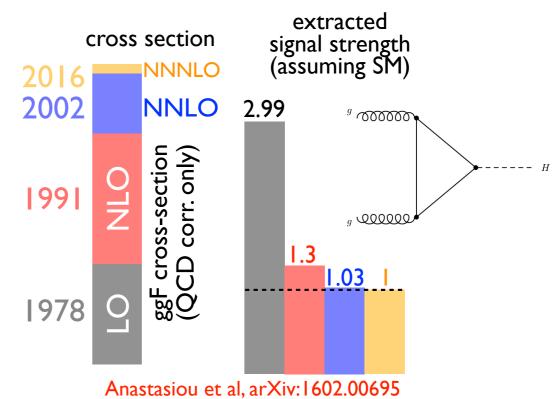




### Standard Model measurements

- The measurement of the Higgs couplings is an emblematic example of the need for precision
  - Large perturbative corrections for the dominant channel (gluon fusion)
  - Without higher-order corrections, measured signal strength ~ 3 × SM
  - Very competitive experimental measurements!







$$\hat{\sigma}_{ab\to X}(\hat{s},\mu_F,\mu_R)$$
 Parton-level cross section

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 Including higher corrections improves predictions and reduces theoretical uncertainties



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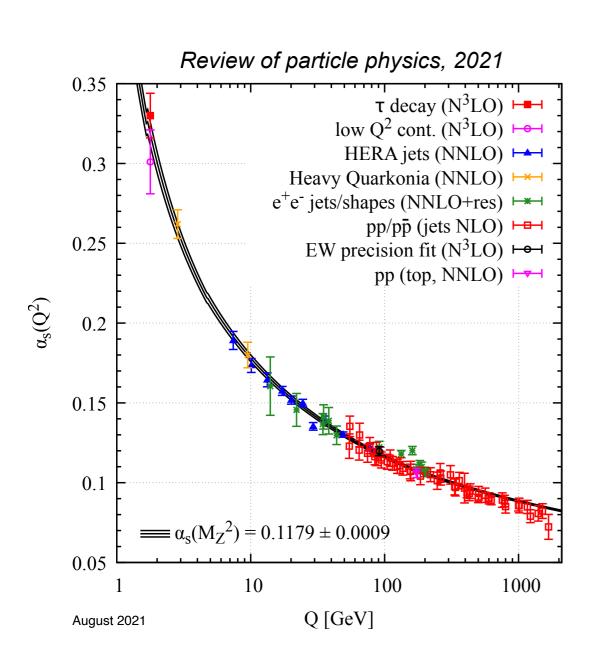
### Renormalisation scale



- Introduced in perturbation theory and "is an unphysical parameter"
- Consequences:
  - The coupling constant depends on this parameter
  - Beyond LO, the matrix elements depend on this parameter
  - Only if on includes all orders in perturbation theory, this parameter drops out
- Which value should you give it?



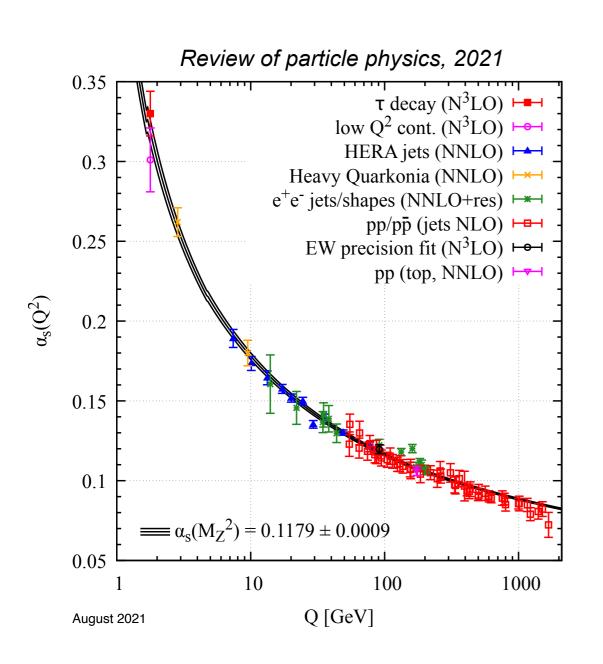
# Running of the strong coupling



- The value of the strong coupling depends (logarithmically) on the renormalisation scale
- The larger the scale, the smaller the coupling
- Naively: choose large renormalisation scales, and perturbation theory will work well...?



# Running of the strong coupling



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- Naively: choose large renormalisation scales, and perturbation theory will work well...?

Not so simple



### Renormalisation scale II

Which value should you give it?

$$\hat{\sigma} = \sigma^{\text{Born}} \left( 1 + \sum_{k=1}^{\infty} \left( \frac{\alpha_s}{2\pi} \right)^k \sigma^{(k)} \right)$$

- For the theory to converge, both  $\alpha_s$  and  $\sigma^{(k)}$  should be small, and both depend on the renormalisation scale
- Just like  $\alpha_s$ , also  $\sigma^{(k)}$  depends logarithmically on the renormalisation scale: it contains (powers of)  $\log(\mu_R^2/Q^2)$ , with  $Q^2$  any (relevant) invariant, such as particle masses, 2-body invariant masses,  $\sqrt{\hat{s}}$ , etc.
- For the best convergence, the renormalisation scale should be chosen such that it matches the typical  $Q^2$  relevant to the process and or observable



### What about the factorisation scale?

$$\hat{\sigma}_{ab o X}(\hat{s}, \mu_H, \mu_R)$$
 Parton-level cross section



## What about the factorisation scale?

$$\hat{\sigma}_{ab o X}(s, \mu_F, \mu_R)$$
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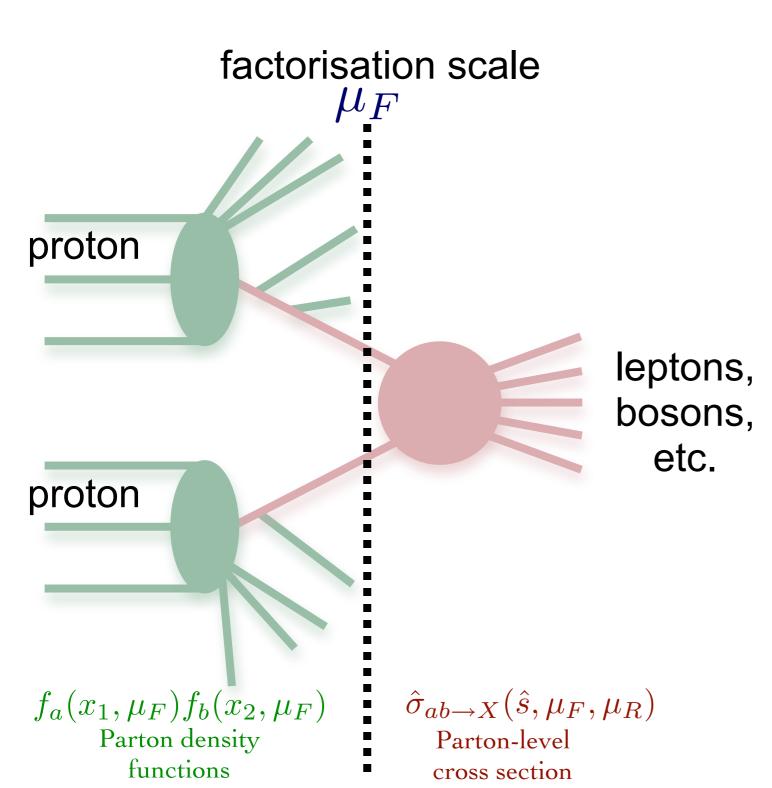


- Has a clearer physical interpretation:
  - Separation scale between physics included in parton density functions and hard matrix elements
  - Just like renormalisation scale, should take a numerical value close to the relevant scale to the process
  - Including higher-orders reduces the dependence on the factorisation scale

$$\sum_{a,b} \int dx_1 dx_2 d\Phi_{\text{FS}} f_a(x_1, \mu_F) f_b(x_2, \mu_F) \, \hat{\sigma}_{ab \to X}(\hat{s}, \mu_F, \mu_R)$$
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### Inclusiveness



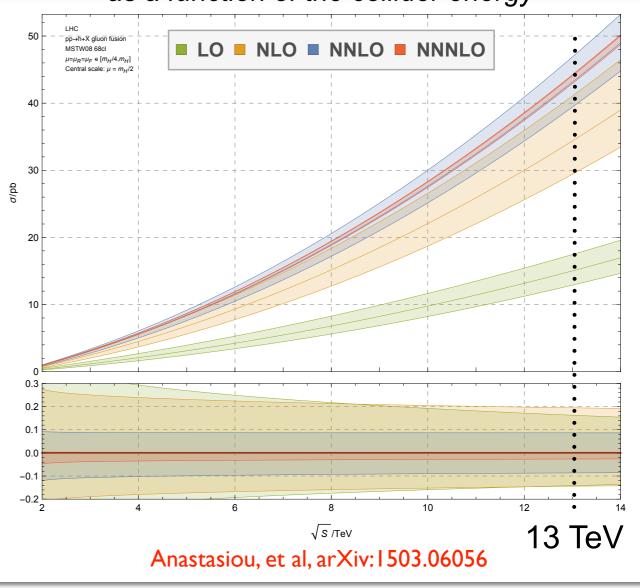
- All additional radiation, softer than the factorisation scale, is included in the computed cross section through the evolution of the parton density functions
  - Only exact in the collinear limit
- At N<sup>k</sup>LO accuracy, up to k of these emissions are included exactly also outside the collinear limit
  - This reduces the dependence on the factorisation scale



# Perturbation theory at work

- The inclusion of higher orders improves the reliability of a given computation
  - More reliable description of total rates and shapes
  - Residual uncertainties related to the arbitrary scales in the process decrease
  - The computational complexity grows exponentially
  - NLO is mandatory for LHC physics!

Cross section for Higgs production in gluon fusion as a function of the collider energy





# Master equation for the hard interaction

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#### In practice: predictions at LO

#### How to calculate e.g. 3-jet production at the LHC?

Identify all subprocesses (gg→ggg, qg→qgg....) in:

$$\sigma(pp \to 3j) = \sum_{ijk} \int f_i(x_1) f_j(x_2) \hat{\sigma}(ij \to k_1 k_2 k_3)$$

easy

For each one, calculate the amplitude

$$\mathcal{A}(\{p\},\{h\},\{c\}) = \sum_{i} D_{i}$$

difficult

 Square the amplitude, sum over spin & colour, and integrate over the phase-space

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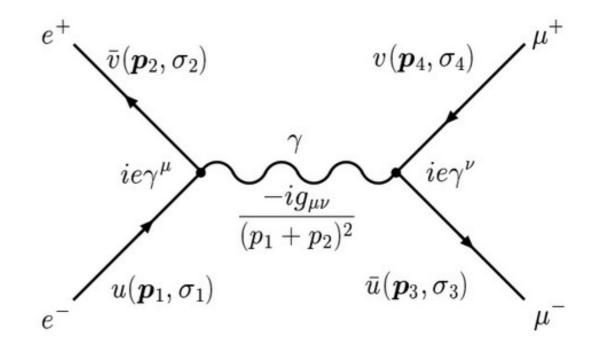
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#### Feynman Rules

- Based on Feynman Rules: universal building blocks to create Feynman diagrams
- Feynman diagrams correspond to mathematical expressions



- Tedious to do by hand, but no problem for a computer
- Using helicity amplitudes with explicit representations for the spinors/polarisation vectors can reduce the complexity in the numerical evaluation of the expressions
- Recycling identical sub-structures in multiple diagrams and/or using recursion relations, can further reduce the computation time



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### Phase-space integral

$$\operatorname{Dim}[\Phi(n)] = 3n - 2$$

$$\sigma = \frac{1}{2s} \int |\mathcal{M}|^2 d\Phi(n)$$

 Calculations of cross section or decay widths involve integrations over the phase space of rather peaked, multivariate functions



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> General and flexible method is needed: Numerical (Monte Carlo) integration

# Monte-Carlo integration: Integrals as averages

Integral as a sum:

$$I = \int_a^b f(x) dx \qquad \qquad I_N = (b-a)\frac{1}{N} \sum_{i=1}^N f(x_i)$$

$$V = (b-a) \int_a^b \left[ f(x) \right]^2 dx - I^2 \qquad \qquad V_N = (b-a)^2 \frac{1}{N} \sum_{i=1}^N \left[ f(x_i) \right]^2 - I_N^2$$

$$I = I_N \pm \sqrt{V_N/N}$$

- Convergence is slow but it can be estimated easily
- Scaling of the error does not depend on # of dimensions!
- Improvement by minimising  $V_{N}$
- Optimal/Ideal case:  $f(x) = \text{constant} \Rightarrow V_N = 0$

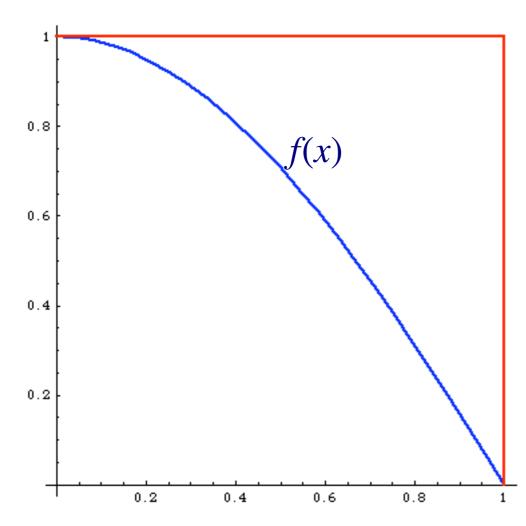


## Event generation

- Every phase-space point computed in this way, can be seen as an event (=collision) in a detector
- However, they still carry the "weight" of the matrix elements:
  - events with large weights where the diff. cross section is large
  - events with small weights where the diff. cross section is small
- In nature, the events don't carry a weight:
  - more events where the diff. cross section is large
  - less events where the diff. cross section is small
- How to go from weighted events to unweighted events?



## Generation of unweighted events



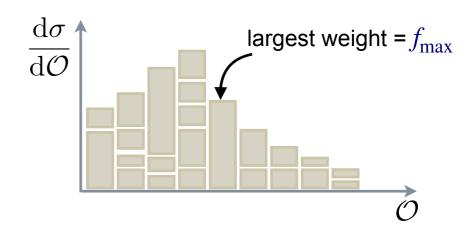
- Integral is area under a graph
  - Instead of picking a random x and compute f(x),
  - pick a random x and y and check if
     f(x) < y. If so, keep event</li>
  - Integral: 'total area' multiplied by fraction of events kept
- "Unweighted" events contain the maximum amount of statistical information in the least amount of events
  - Ideal if post-processing (slow detector simulation!) or storage is at a premium
- It requires knowledge on  $f_{\text{max}}$  to determine the 'total area'.



## Unweighting in multiple dimensions

- Procedure works the same in multiple dimensions
- In practice,  $f_{\rm max}$  is determined dynamically: event with largest weight encountered

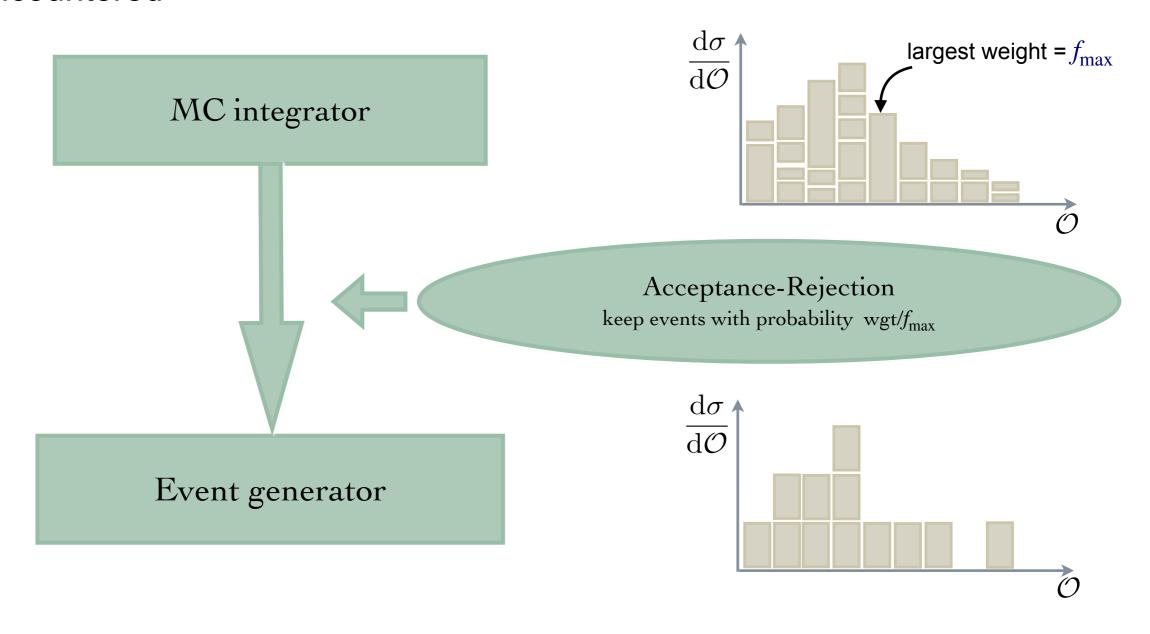
MC integrator





## Unweighting in multiple dimensions

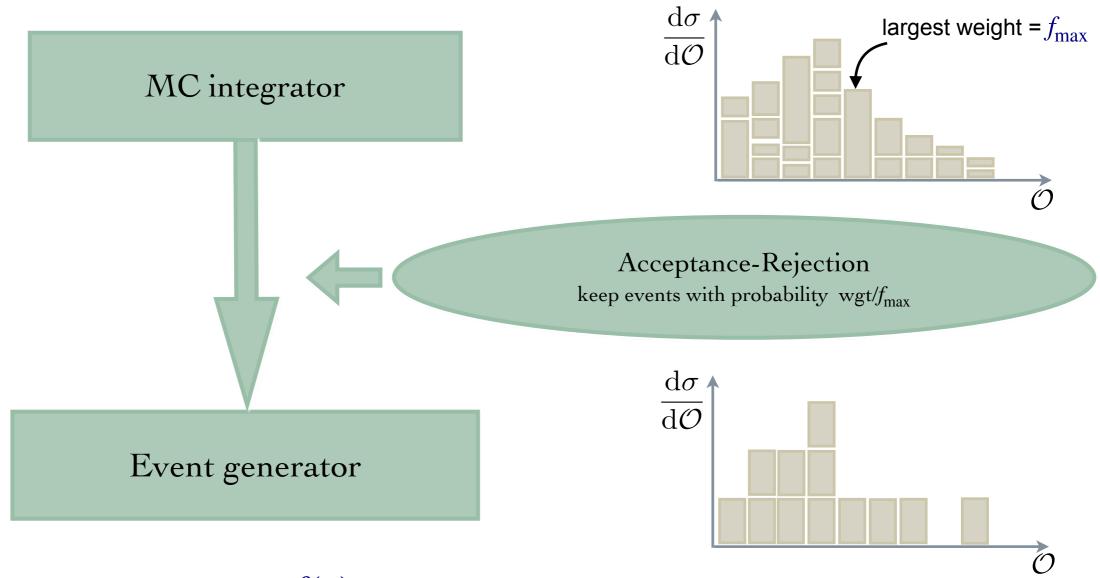
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• This is possible only if f(x) is bounded (and has definite sign)!



### Curse of dimensionality

- Error in Monte-Carlo integration scales like  $1/\sqrt{N}$ , with N the number of sampling points, independently of the number of dimensions. However...
  - the variance among the points is (typically) much larger for high dimensions: more complicated integrands
  - increasing the dimensions makes the available space much larger
- This makes phase-space integration for multi-particle processes a very hard problem

Number of Dimensions	Nearest Nghbr. Distance
1	5.0 x 10 <sup>-5</sup>
2	5.0 x 10 <sup>-3</sup>
3	2.6 x 10 <sup>-2</sup>
4	6.3 x 10 <sup>-2</sup>
5	0.11
7	0.23
10	0.39
25	1.1

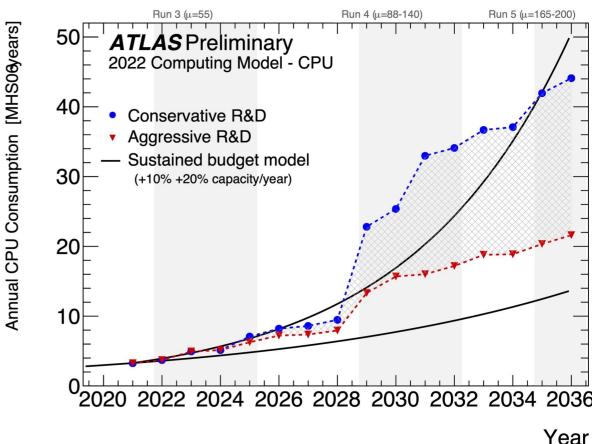
(average) nearest-neighbour distance among 10000 randomly generated points in a unit hypercube



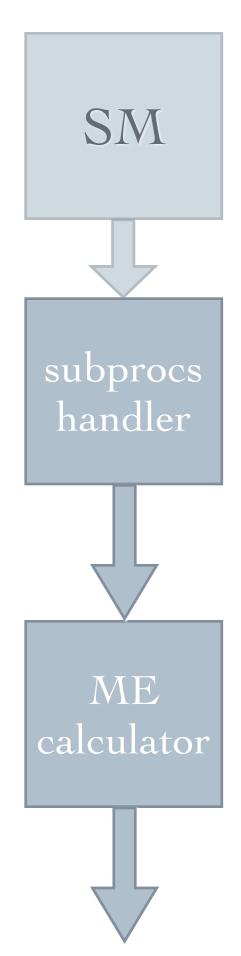
## Optimisation

- Optimising phase-space integration and event unweighting can easily reduce the computation time by orders of magnitude
  - Typically much more than optimising the evaluation time of the matrix elements (at least for tree-level contributions)
- A very active area of research!
  - Some recent progress:
    - Optimised phase-space parametrisation
       [E. Bothmann et al. 2023]
    - Massively parallel setups
       [E. Bothmann et al. 2022, 2023]

#### Expectation: computation needs HL-LHC



- Normalising flows and Machine Learning for efficient phase-space point generation
  [T. Heimel et al. 2022, 2023, 2024]
- Reweighting low-accuracy events to high-accuracy [RF & T. Vitos, in preparation]





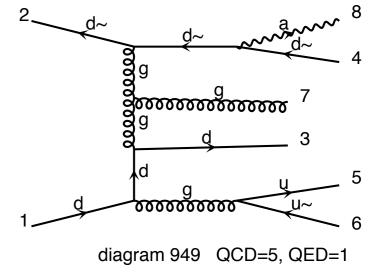
# ME generators: general structure

Includes all possible subprocess leading to a given multi-jet final state automatically or manually (done once for all)

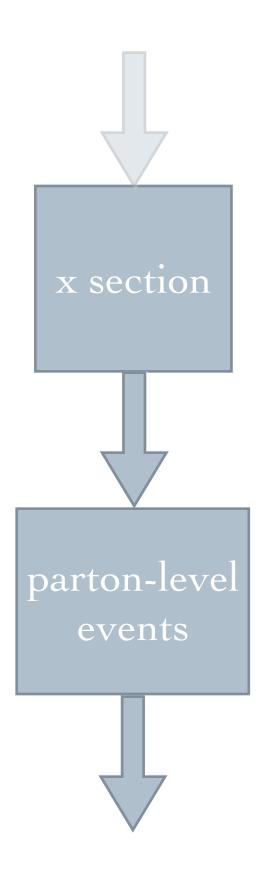
d~ d -> a d d~ u u~ g d~ d -> a d d~ c c~ g s~ s -> a d d~ u u~ g s~ s -> a d d~ c c~ g ...

"Automatically" generates a code to calculate |M|<sup>2</sup> for arbitrary processes with many partons in the final state.

Use Feynman diagrams with tricks to reduce the factorial growth, others have recursive relations to reduce the complexity to exponential.

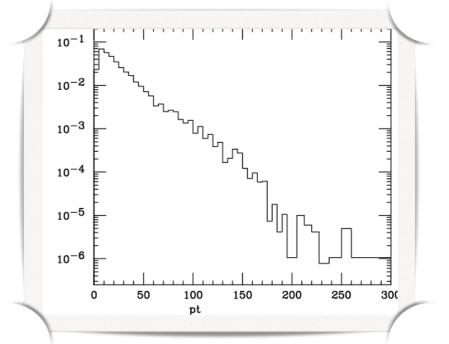






# ME generators: general structure

Integrate the matrix element over the phase space using importance sampling and a multi-channel technique and using parton-level cuts.

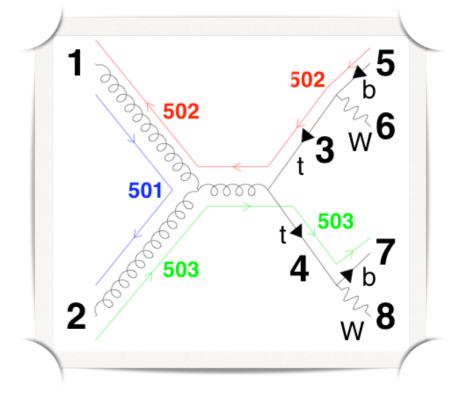


Events are obtained by unweighting.

These are at the parton-level.

Information on particle id, momenta, spin, color is given in the Les Houches Event (LHE)

File format.





- All three steps change when including higher orders
- Let's focus on NLO. (NNLO and beyond imposes similar technical challenges, but orders of magnitude more complex)



#### In practice: predictions at LO

How to calculate e.g. 3-jet production at the LHC?

Identify all subprocesses (gg→ggg, qg→qgg....) in:

$$\sigma(pp \to 3j) = \sum_{i,j,k} \int f_i(x_1) f_j(x_2) \hat{\sigma}(ij \to k_1 k_2 k_3)$$

easy

• For each one, calculate the amplitude

$$\mathcal{A}(\{p\},\{h\},\{c\}) = \sum_{i} D_{i}$$

difficult

 Square the amplitude, sum over spin & colour, and integrate over the phase-space

$$\hat{\sigma} = \frac{1}{2\hat{s}} \int d\Phi_p \sum_{h,c} |\mathcal{A}|^2$$

quite hard



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The same subprocesses contribute, and

need also subprocesses with one more parton



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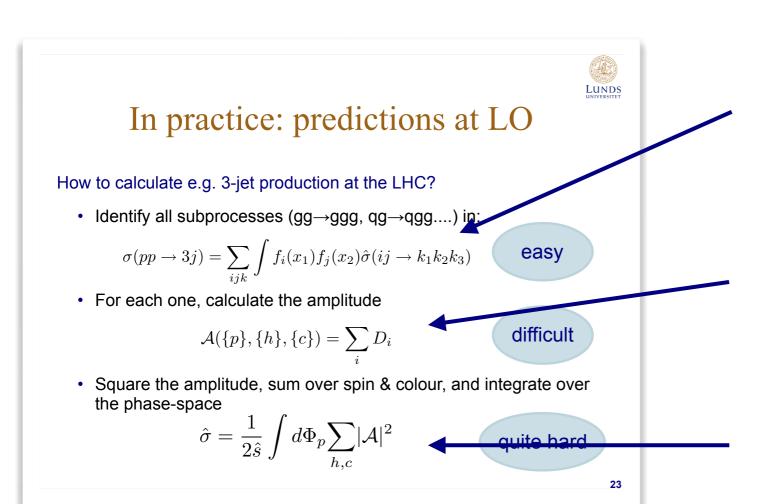
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Lunds



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The same subprocesses contribute, and

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The same amplitudes need to be included, and

 need also generate amplitudes with particles going in a loop

Still need to integrate over the phasespace,

need also to cancel divergencies



#### NLO: how to?

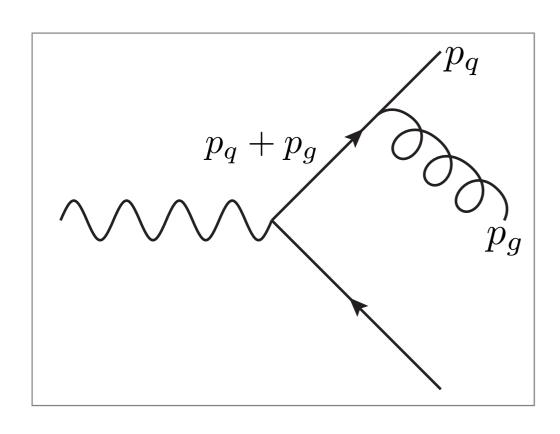
Three ingredients need to be computed at NLO

$$\sigma_{NLO} = \int_{n} \alpha_{s}^{b} d\sigma_{0} + \int_{n} \alpha_{s}^{b+1} d\sigma_{V} + \int_{n+1} \alpha_{s}^{b+1} d\sigma_{R}$$
Born Virtual Real-emission corrections

 Remember: virtual and reals are not separately finite, but their sum is (KLN theorem). Divergences have to be subtracted before numerical integration



### IR-singularities in the real emission



$$\int_{n+1} \alpha_s^{b+1} d\sigma_R$$

- When the integral over the phase- space of the gluon is performed, one can have  $(p_q + p_g)^2 = 0$
- Since  $(p_q+p_g)^2=2E_qE_g(1-\cos\theta)$ , it can happen when  $E_g=0$  (soft) or  $\cos\theta=1$  (collinear)
- In both cases, the propagator diverges



# IR-singularities in the virtual corrections

- The same IR singularities as in the real-emission corrections also appear in the (renormalised) virtual corrections, but with opposite sign. (Follows from KLN theorem!)
  - Virtual corrections: integration over the loop momenta gives poles in  $1/\epsilon$ , with  $\epsilon$  the dimensional regulator
  - Real corrections: integration over the phase-space gives poles in  $1/\epsilon$ , with  $\epsilon$  the dimensional regulator
- Problematic! Integration over the phase-space is performed numerically. Cannot be done in a non-integer number of dimensions!
- Note: observables must not be sensitive to collinear/soft real emission branching (i.e., for KLN to be applicable). Hence, must use "infrared-safe" observables, and cannot use infinite resolution
- No problem in the virtual corrections: integration over the loop momentum is typically done (semi-)analytically, so poles in  $\epsilon$  and the finite remainder can be computed explicitly



### Example

Suppose we want to compute the integral

$$\int_0^1 f(x) \, dx, \text{ with } f(x) = \frac{g(x)}{x} \text{ and } g(x) \text{ a regular function}$$

Let's introduce a regulator, which renders the integral finite

$$\int_0^1 f(x) \, \mathrm{d}x \longrightarrow \int_0^1 x^{\epsilon} f(x) \, \mathrm{d}x = \int_0^1 \frac{g(x)}{x^{1-\epsilon}} \, \mathrm{d}x$$

and in the end we take the limit  $\epsilon \to 0$ 



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#### Phase-space slicing

• Introduce a small parameter  $\delta$ :

$$\int_0^1 \frac{g(x)}{x^{1-\epsilon}} dx = \int_0^\delta \frac{g(x)}{x^{1-\epsilon}} dx + \int_\delta^1 \frac{g(x)}{x^{1-\epsilon}} dx$$

$$\simeq \int_0^\delta \frac{g(0)}{x^{1-\epsilon}} dx + \int_\delta^1 \frac{g(x)}{x^{1-\epsilon}} dx$$

$$= \left(\frac{1}{\epsilon} + \log \delta\right) g(0) + \int_\delta^1 \frac{g(x)}{x} dx$$

where we have taken the limit  $\epsilon \to 0$  in the 2<sup>nd</sup> term



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#### Subtraction method

• Add and subtract g(0)/x:

$$\int_{0}^{1} \frac{g(x)}{x^{1-\epsilon}} dx = \int_{0}^{1} x^{\epsilon} \left( \frac{g(0)}{x} + \frac{g(x)}{x} - \frac{g(0)}{x} \right) dx$$

$$= \int_{0}^{1} \frac{g(0)}{x^{1-\epsilon}} dx + \int_{0}^{1} \frac{g(x) - g(0)}{x^{1-\epsilon}} dx$$

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- Both methods have a simple *universal* integral to be done *analytically* (that yields the pole to be canceled against the pole in the virtual corrections); and a complicated *finite* integral to be performed *numerically*
- Since no approximation in the subtraction method, this is the preferred method at NLO
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$$\int_0^1 f(x) \, \mathrm{d}x \longrightarrow \int_0^1 x^{\epsilon} f(x) \, \mathrm{d}x = \int_0^1 \frac{g(x)}{x^{1-\epsilon}} \, \mathrm{d}x$$

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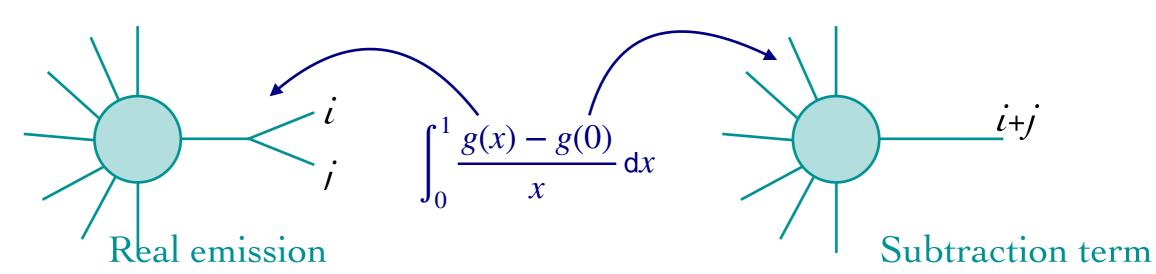
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# NLO: kinematics of subtraction



#### terms



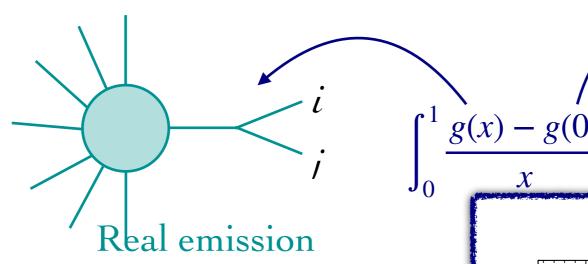
- Real emission and subtraction term cannot be separated (individually, they are divergent!)
- i and j are on-shell in the real emission, but i+j is not:  $x\sim m_{i+j}^2$  i+j must be on-shell in the subtraction term
  - This is not possible without reshuffling the momenta of other particles in the process: hence each "event" has two sets of kinematics
  - If can happen, real-emission and the subtraction terms end-up in different histogram bins
    - Use IR-safe observables and don't ask for infinite resolution! (KLN theorem)

### NLO: kinematics of subtraction

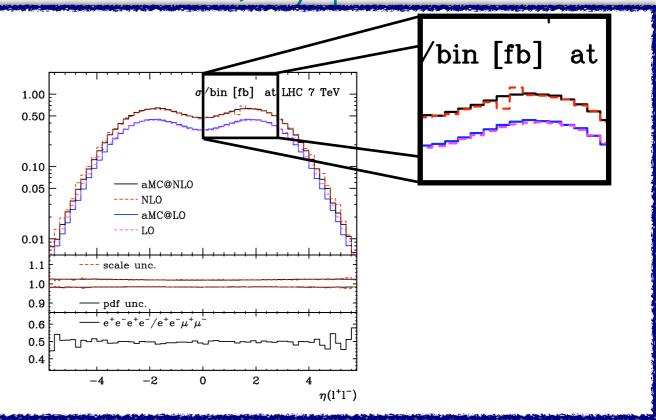


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- Another consequence of the kinematic mismatch is that we cannot generate unweighted events at NLO
  - n + 1-body contribution and n-body contribution are not bounded from above → unweighting not possible
  - Further ambiguity on which kinematics to use for the unweighted events



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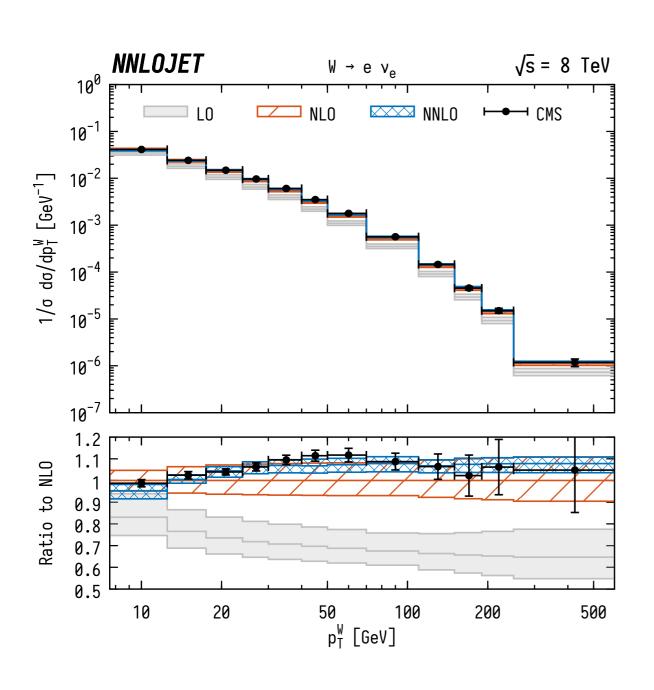
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For NLO event generation (and parton-shower matching) we need additional work more on this in the next lecture(s)



## Example: W+j production

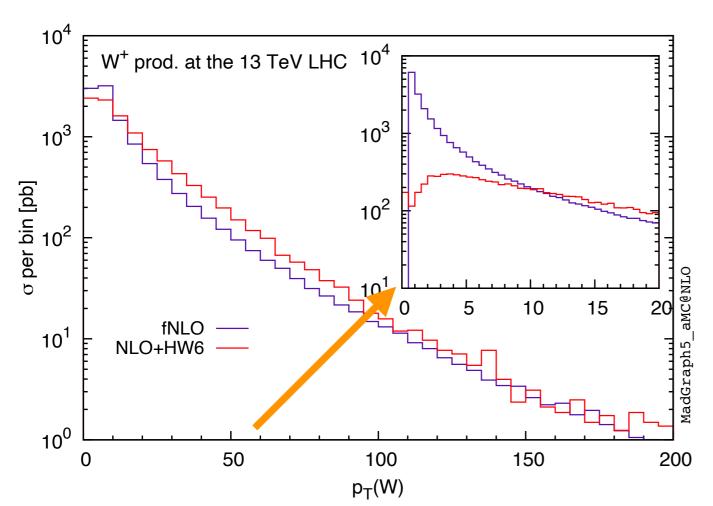


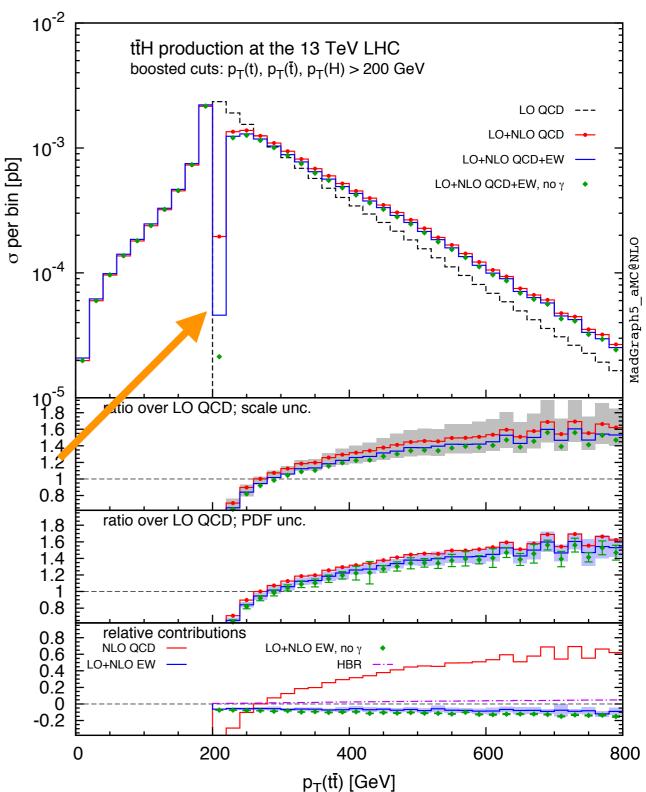
- Both NLO and NNLO agree with the CMS data (8 TeV collisions),
  - NNLO has significantly smaller uncertainties
- LO uncertainties underestimated
  - In general: NLO accuracy required to describe LHC data



#### Instabilities at fixed order

• Besides the mis-binning problem, the kinematics mismatch can lead to odd behaviours of certain observables, in particular when some constraint coming from the n-body kinematics is relaxed in the n+1-body one





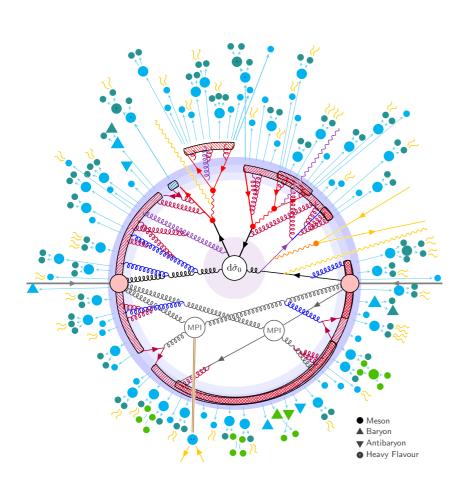


#### Summary: the hard interaction

- Event generators are there to bridge the gap between theory concepts and experimental concepts
- At the heart, we have a matrix-element generator
- Most-difficult part: Phase-space integration by using Monte-Carlo techniques
  - scales very good with number of dimensions
  - also works with involved integration boundaries (cuts!)
  - allows for event simulation
- For the generation of "unweighted" events, an acceptance/ rejection step needs to be performed



#### Summary: the hard interaction



- Only discussed the central part of the collision.
- Sometimes this is enough!
  - No matching to parton shower
  - Easy to go beyond LO
  - Analytic resummation (instead of resummation with PS also a way forward, and possibly higher accuracy)

$$\sum_{a,b} \int dx_1 dx_2 d\Phi_{\mathrm{FS}} \, f_a(x_1, \mu_F) f_b(x_2, \mu_F) \, \hat{\sigma}_{ab \to X}(\hat{s}, \mu_F, \mu_R)$$
Phase-space Parton density Parton-level cross integral functions section